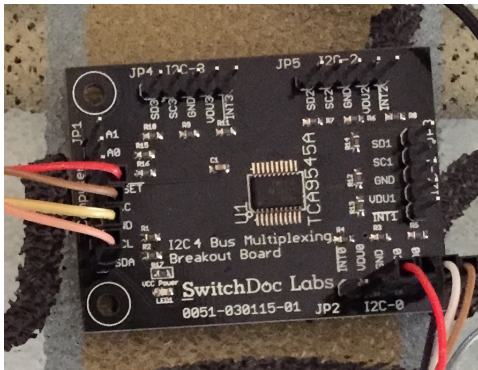


The **I2CMux Breakout Board** is an easy to use 4 Channel I2C Multiplexer.

The I2C Mux Breakout Board is a quad bidirectional translating switch controlled via the I2C bus. The SCL/SDA controlling fans out to four downstream channels. Any individual channel or combination of channels can be selected via I2C. It is based on the TCA9545A.

### Features and Benefits:

- Converts one I2C bus (on Pi or Arduino) to 4 separate I2C buses
- Allows using same I2C addresses for many sensors
- Works with Arduino and Raspberry Pi
- 1-of-4 Bidirectional Translating Switches
- Four Active-Low Interrupt Inputs
- Active-Low Interrupt Output
- Active-Low Reset Input
- Two Address Terminals
- Channel Selection via I2C Bus, in Any Combination
- Allows Voltage-Level Translation Between 1.8-V, 2.5-V, 3.3-V, and 5-V Buses
- No Glitch on Power-Up
- Power-Supply Range of 1.65 V to 5.5 V
- Software Drivers for Arduino and Raspberry Pi
- Low Cost
- Quantity Discounts Available
- Immediate Availability



## Introduction

The I2C Mux Breakout Board is a quad bidirectional translating switch controlled via the I2C bus. The SCL/SDA controlling fans out to four downstream channels.

At SwitchDoc Labs, we love data. And we love I2C devices.

We like to gather the data using lots of I2C devices on our computers and projects. Project Curacao has a total of 12 devices and SunRover will have over 20 and will require one I2C bus just for controlling the motors. In addition, we run into

conflicts with addressing on the I2C device. Since there are no standards, sometimes multiple devices will have the same address, such as 0x70 and you are just out of luck in running both of them on the same I2C bus without a lot of jimmy rigging.

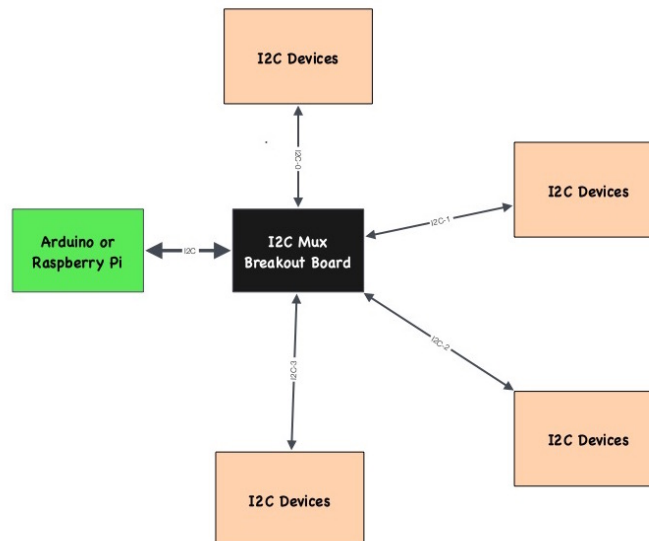
What is the solution for this? **It's an I2C controlled 4 I2C bus multiplexer!**

## How To Use

The I2C Mux Breakout Board is a quad bidirectional translating switch controlled via the I2C bus. The SCL/SDA controlling fans out to four downstream channels.

To use the I2C Mux Breakout Board, you connect the I2C bus up to an Arduino or Raspberry Pi and then connect the additional I2C busses as shown below. The main I2C bus can be 3.3V or 5.0V as well as each of the multiplexed bus can be individually selected as 3.3V or 5.0V I2C busses. There are three things to note when you wire up your I2C Mux Breakout Board.

- If you are not driving your RESET line with a GPIO pin, you must connect it to VCC. Otherwise, the board will not respond.
- Each of the four multiplexed I2C busses must be connected to either 3.3V or 5.0V. Each multiplexed bus is individually powered.
- Unlike other SwitchDoc Labs Breakout Boards, there is a 10K Ohm Pullup on the main I2C lines to VCC and 10K Pullups on each of the Multiplexed I2C busses to their respective power supplies.





## Wiring List

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Raspberry Pi (A/B/A+/B+/Pi 2)

Signal Name	Raspberry Pi A/B/A+/B+/Pi 2	I2CMux Breakout Board
<b>SDA</b>	I2C1_SDA (GPIO/3)	SDA (JP1/1)
<b>SCL</b>	I2C1_SCL (GPIO/5)	SCL (JP1/2)
<b>GND</b>	GND (GPIO/6)	GND (JP1/3)
<b>Power</b>	3.3V (GPIO/1)	VCC (JP1/4)
<b>Reset</b>	3.3V (GPIO/1)	RESET' (JP1/5)
<b>Int</b>	GPIO 18 (GPIO/12)	INT' (JP1/6)
<b>Address Select 0</b>	N/C	A0 (JP1/7)
<b>Address Select 1</b>	N/C	A1 (JP1/8)

## Arduino Uno

Signal Name	Arduino Uno	I2CMux Breakout Board
SDA	ADC4/SDA (ANALOG IN/A4)	SDA (JP1/1)
SCL	ADC5/SCL (ANALOG IN/A5)	SCL (JP1/2)
GND	GND (POWER/GND)	GND (JP1/3)
Power	5.0V (POWER/5V)	VCC (JP1/4)
Reset	5.0V (POWER/5V)	RESET' (JP1/5)
Int	INT0 (DIGITAL/2)	INT' (JP1/6)
Address Select 0	N/C	A0 (JP1/7)
Address Select 1	N/C	A1 (JP1/8)

## Arduinio Mega 2560

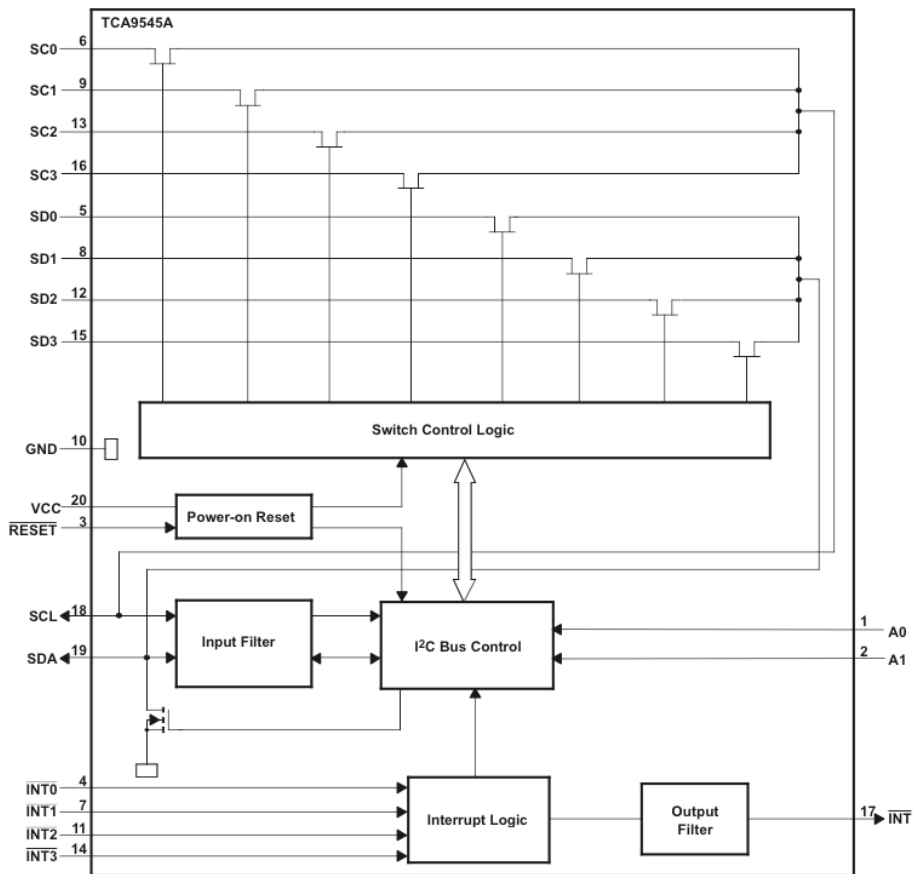
Signal Name	Arduino Mega 2560	I2CMux Breakout Board
SDA	SDA (COMMUNICATIONS 20)	SDA (JP1/1)
SCL	SCL (COMMUNICATIONS 21)	SCL (JP1/2)
GND	GND (POWER/GND)	GND (JP1/3)
Power	5.0V (POWER/5V)	VCC (JP1/4)
Reset	5.0V (POWER/5V)	RESET' (JP1/5)
Int	INT4 PWM/2)	INT' (JP1/6)
Address Select 0	N/C	A0 (JP1/7)
Address Select 1	N/C	A1 (JP1/8)

### Theory of Operation

#### TCA9545A IC

For more information, see the full TCA9545A Specification at: <http://www.ti.com/lit/ds/symlink/tca9545a.pdf>

The TCA9545A is a quad bidirectional translating switch controlled via the I2C bus. The SCL/SDA upstream pair fans out to four downstream pairs, or channels. Any individual SCn/SDn channel or combination of channels can be selected, determined by the contents of the programmable control register. Four interrupt



inputs (INT3'–INT0'), one for each of the downstream pairs, are provided. One interrupt (INT') output acts as an AND of the four interrupt inputs.

An active-low reset (RESET') input allows the TCA9545A to recover from a situation in which one of the downstream I2C buses is stuck in a low state. Pulling RESET low resets the I2C state machine and causes all the channels to be deselected, as does the internal power-on reset function.

The pass gates of the switches are constructed such that the VCC terminal can be used to limit the maximum high voltage, which will be passed by the TCA9545A. This allows the use of different bus voltages on each pair, so that 1.8-V, 2.5-V, or 3.3-V parts can communicate with 5-V parts, without any additional protection. External pull-up resistors pull the bus up to the desired voltage level for each channel. All I/O terminals are 5.5 V tolerant.

## Operating Values

		Min	Normal	Max	Unit
VCC	Supply Voltage	2.7		5.5	V
VDU0, VDU1, VDU2, VDU3	Multiplexed I2C Bus Supply Voltages	2.7		5.5	V

## Pin Locations

Physical dimensions of board: 50mm x 37mm x 12mm(max).

### I/O Key:

**I** - Digital Input  
**O** - Digital Output  
**A** - Analog

## Pin Functions

### JP1 - Computer Side Pins

Input / Output Control Lines for I2CMux Breakout Board

NAME	PIN	I/O	DESCRIPTION
SDA	JP1 / 1	I/O	Serial bus data line; open-drain input/output. Tied to VCC with 10K Ohm Pullup
SCL	JP1 / 2	I	Serial bus clock line; open-drain input. Tied to VCC with 10K Ohm Pullup
GND	JP1 / 3	A	GND
VCC	JP1 / 4	A	Power for the I2CMux Breakout Board. Use 3.3V with Raspberry Pi and 5.0V with Arduino
RESET'	JP1 / 5	I	Reset Board; open-drain input.
INT'	JP1 / 6	O	Interrupt from Board; open-drain output.
A0	JP1 / 7	I	A0 Address Input. 10K Pullup to VCC. I2C Address range from 0x70 - 0x73. Default 0x73
A1	JP1 / 8	I	A1 Address Input. 10K Pullup to VCC. I2C Address range from 0x70 - 0x73. Default 0x73

### JP2 - Multiplexed I2C Bus 0

Multiplexed I2C Bus 0. All buses can have different power supplies

NAME	PIN	I/O	DESCRIPTION
INT0'	JP2 / 1	I	Open Drain Input for I2C Bus 0 Input. Tied to VDU0 with 10K Pullup
VDU0	JP2 / 2	A	Power Supply for I2C Bus 0. Tie to 3.3V or 5.0V.
GND	JP2 / 3	A	GND
SC0	JP2 / 4	O	Serial bus clock line; open-drain output. Tied to VDU0 with 10K Pullup
SD0	JP2 / 5	I/O	Serial bus data line. open-drain input/output. Tied to VDU0 with 10K Pullup



**JP3 - Multiplexed I2C Bus 1**

Multiplexed I2C Bus 1. All buses can have different power supplies

NAME	PIN	I/O	DESCRIPTION
INT1'	JP3 / 1	I	Open Drain Input for I2C Bus 1 Input. Tied to VDU1 with 10K Pullup
VDU1	JP3 / 2	A	Power Supply for I2C Bus 1. Tie to 3.3V or 5.0V.
GND	JP3 / 3	A	GND
SC1	JP3 / 4	O	Serial bus clock line; open-drain output. Tied to VDU1 with 10K Pullup
SD1	JP3 / 5	I/O	Serial bus data line. open-drain input/output. Tied to VDU1 with 10K Pullup

**JP5 - Multiplexed I2C Bus 2 (NOTE: JP5 IS BUS 2!)**

Multiplexed I2C Bus 2. All buses can have different power supplies

NAME	PIN	I/O	DESCRIPTION
INT2'	JP5 / 1	I	Open Drain Input for I2C Bus 2 Input. Tied to VDU2 with 10K Pullup
VDU2	JP5 / 2	A	Power Supply for I2C Bus 2. Tie to 3.3V or 5.0V.
GND	JP5 / 3	A	GND
SC2	JP5 / 4	O	Serial bus clock line; open-drain output. Tied to VDU2 with 10K Pullup
SD2	JP5 / 5	I/O	Serial bus data line. open-drain input/output. Tied to VDU2 with 10K Pullup

### JP4 - Multiplexed I2C Bus 3 (NOTE: JP4 is BUS 3!)

Multiplexed I2C Bus 3. All buses can have different power supplies

NAME	PIN	I/O	DESCRIPTION
INT3'	JP4 / 1	I	Open Drain Input for I2C Bus 3 Input. Tied to VDU3 with 10K Pullup
VDU3	JP4 / 2	A	Power Supply for I2C Bus 3. Tie to 3.3V or 5.0V.
GND	JP4 / 3	A	GND
SC3	JP4 / 4	O	Serial bus clock line; open-drain output. Tied to VDU3 with 10K Pullup
SD3	JP4 / 5	I/O	Serial bus data line. open-drain input/output. Tied to VDU3 with 10K Pullup

### Software for Arduino and Raspberry Pi

SwitchDoc Labs developed this pure Python TCA9545A I2CMux Raspberry Pi library and the Arduino Library and have posted them on the SwitchDoc Labs Respository on [github.com](https://github.com)

The Raspberry Pi Pure Python software is here: [https://github.com/switchdoclabs/SDL\\_Pi\\_TCA9545](https://github.com/switchdoclabs/SDL_Pi_TCA9545)

The Arduino Software is here: [https://github.com/switchdoclabs/SDL\\_Arduino\\_TCA9545A](https://github.com/switchdoclabs/SDL_Arduino_TCA9545A)

Using the Arduino libraries and the test software show the following result. The test setup is to connect an additional I2C device to Bus0 - in this case a SwitchDoc Labs INA3221 Breakout Board at address 0x40 on Bus0.

```

-----
-----
SDA_Arduino_TCA9545_Test
Reading all four I2C Buses
-----
-----
-----
-----
-----
-----
Bus 0 Control Register:1

```

```
Scanning...  
I2C device found at address 0x40 !  
I2C device found at address 0x73 !  
done
```

```
-----  
Bus 1 Control Register:2  
Scanning...  
I2C device found at address 0x73 !  
done
```

```
-----  
Bus 2 Control Register:4  
Scanning...  
I2C device found at address 0x73 !  
done
```

```
-----  
Bus 3 Control Register:8  
Scanning...  
I2C device found at address 0x73 !  
done
```

Repeat the above test connecting the I2C Device to Bus1, Bus2 and Bus3

The I2C device (the INA3221 in my case) will move from bus to bus.